

壳体中性曲面变形后的度量张量和曲率张量

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摘要: 为了从数学角度更好地描述壳体中性曲面如何变形, 通过渐近分析和张量分析, 给出了当壳体中性曲面发生形变时度量张量和曲率张量改变量的完整表达式. 提出的度量张量的改变量与 Ciarlet 给出的一致, 而曲率张量的改变量比 Ciarlet 给出的更精确. 由于度量张量和曲率张量的改变量是构造 Koiter 型线性、非线性弹性壳体模型的重要组成部分, 因此提出新的 Koiter 型非线性弹性壳体模型, 理论上比 Ciarlet 的非线性模型误差更小. 这为火箭、导弹、航天飞船等国防领域和火车、汽车等工业领域的研究提供了更好的数学基础.

关键词: 度量张量; 曲率张量; 渐近分析; 张量分析

中图分类号: O242 **文献标识码:** A **文章编号:** 0253-987X(2007)12-1483-04

Metric Tensor and Curvature Tensor in Deformed Shell Middle Surface

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Abstract: To mathematically characterize the deformation of the middle surface of a shell, the metric tensor and curvature tensor ought to be investigated in detail. Based on the definitions of metric tensor and curvature tensor, the full expressions of their changes are put forward with asymptotic analysis, where the metric tensor change expression coincides with Ciarlet's, and the curvature tensor change expression is described more accurately than Ciarlet's. Then a new non-linear shell model of Koiter's type is constructed with smaller error than in Ciarlet's theory for the fields of national defense, such as rockets, missiles, aircrafts, and for the fields of industry, such as trains and cars.

Keywords: metric tensor; curvature tensor; asymptotic analysis; tensor analysis

本文研究了壳体中性面 S 变形为 $S(\boldsymbol{\eta})$ 时, 其度量张量和曲面张量是如何变化的. 最近, Ciarlet 将度量张量和曲率张量的改变量作为新的未知变量, 从微分几何的观念来研究壳体模型^[1-3], 因此研究度量张量和曲率张量的改变量显得重要.

20 世纪 60 年代, Koiter 通过渐近分析提出了一个二维的壳体模型, 称为 Koiter 模型, 有如下形式^[4-5].

求 $\boldsymbol{\eta} \in \mathbf{V}_K(\boldsymbol{\omega}) = \{\boldsymbol{\eta} = (\eta^j) \in H^1(\boldsymbol{\omega}) \times H^1(\boldsymbol{\omega}) \times H^2(\boldsymbol{\omega}); \eta^j = \partial_n \eta^3 = 0 \text{ on } \gamma\}$
满足

$$\begin{aligned} & \frac{\varepsilon}{4} \iint_{\boldsymbol{\omega}} a^{\alpha\beta\sigma\tau} (a_{\sigma\tau}(\boldsymbol{\eta}) - a_{\sigma\tau}) (a_{\alpha\beta}(\boldsymbol{\zeta}) - a_{\alpha\beta}) a^{1/2} dx + \\ & \frac{\varepsilon^3}{3} \iint_{\boldsymbol{\omega}} a^{\alpha\beta\sigma\tau} (b_{\sigma\tau}(\boldsymbol{\eta}) - b_{\sigma\tau}) (b_{\alpha\beta}(\boldsymbol{\zeta}) - b_{\alpha\beta}) a^{1/2} dx = \\ & \iint_{\boldsymbol{\omega}} \mathbf{p} \cdot \boldsymbol{\zeta} a^{1/2} dx \quad \forall \boldsymbol{\zeta} \in \mathbf{V}_K(\boldsymbol{\omega}) \end{aligned}$$

式中: $a^{\alpha\beta\sigma\tau}$ 是二维弹性张量的逆变分支; $a_{\alpha\beta}(\boldsymbol{\zeta}) - a_{\alpha\beta}$ 和 $b_{\alpha\beta}(\boldsymbol{\zeta}) - b_{\alpha\beta}$ 分别是与壳体中性面 S 上的位移场 $\boldsymbol{\eta}$ 相关的度量张量和曲率张量改变量的协变分支; $\mathbf{p} \in L^2(\boldsymbol{\omega})$ 是外力. 显而易见, Koiter 模型的线性、非线性依赖于 $a_{\alpha\beta}(\boldsymbol{\zeta}) - a_{\alpha\beta}$ 和 $b_{\alpha\beta}(\boldsymbol{\zeta}) - b_{\alpha\beta}$ 的线性、非线性. Ciarlet 给出了 $a_{\alpha\beta}(\boldsymbol{\zeta}) - a_{\alpha\beta}$ 和 $b_{\alpha\beta}(\boldsymbol{\zeta}) - b_{\alpha\beta}$

$b_{\alpha\beta}$ 的逼近表达式,从而提出了 Koiter 型非线性弹性壳体模型^[6-7].

本文给出了度量张量和曲率张量改变量的精确表达式,前者与 Ciarlet 给出的一致,后者比 Ciarlet 给出的更精确.因此,我们也可以构造出新的 Koiter 型非线性弹性壳体模型,从理论上讲,新的模型比 Ciarlet 的模型更精确,误差更小,这将在另一篇文章中讨论.

1 预备知识

文中所有拉丁指标 $i, j, k, \dots$ 在集合 $\{1, 2, 3\}$ 中取值,希腊指标 $\alpha, \beta, \gamma, \dots$ 在 $\{1, 2\}$ 中取值,此外 Einstein 指标缩并法则也在文中使用. $\mathbf{a}, \mathbf{b} \in R^3$, 其内积和外积分别记为 $\mathbf{a} \cdot \mathbf{b}$ 和 $\mathbf{a} \wedge \mathbf{b}$. 令 $\bar{\omega}$ 是 R^2 中的一个有界连通开子集,其边界 γ 是 Lipschitz 连续,且 $\bar{\omega}$ 在 γ 一侧. $\mathbf{y} = (y^\alpha)$ 是 $\bar{\omega}$ 的一个内点, $\partial_\alpha := \partial/\partial y^\alpha$. 映射 $\boldsymbol{\theta} \in C^2(\bar{\omega}; R^3)$ 使得向量 $\mathbf{e}_\alpha(\mathbf{y}) := \partial_\alpha \boldsymbol{\theta}(\mathbf{y})$ 在点 $\mathbf{y} \in \bar{\omega}$ 处线性独立. 这两个向量在点 $\boldsymbol{\theta}(\mathbf{y})$ 处张成曲面 $S := \boldsymbol{\theta}(\bar{\omega})$ 的切平面,曲面 S 在点 $\boldsymbol{\theta}(\mathbf{y})$ 的单位法向为 $\mathbf{n}(\mathbf{y}) = \mathbf{e}_3(\mathbf{y}) := \frac{\mathbf{e}_1(\mathbf{y}) \wedge \mathbf{e}_2(\mathbf{y})}{|\mathbf{e}_1(\mathbf{y}) \wedge \mathbf{e}_2(\mathbf{y})|}$, 则向量 $\mathbf{e}_i(\mathbf{y})$ 构成点 $\boldsymbol{\theta}(\mathbf{y})$ 处的协变基,由关系式 $\mathbf{e}^i(\mathbf{y}) \cdot \mathbf{e}_j(\mathbf{y}) = \delta_j^i$ 确定的 $\mathbf{e}^i(\mathbf{y})$ 也构成点 $\boldsymbol{\theta}(\mathbf{y}) \in S$ 处的逆变基,其中 δ_j^i 是 Kronecker 符号(注意 $\mathbf{e}^3(\mathbf{y}) = \mathbf{e}_3(\mathbf{y})$ 和 $\mathbf{e}^\alpha(\mathbf{y})$ 也构成 S 在点 $\boldsymbol{\theta}(\mathbf{y})$ 处的且平面). S 上的度量张量的协变、逆变分支 $a_{\alpha\beta}$ 和 $a^{\alpha\beta}$, Christoffel 记号为 $\Gamma_{\alpha\beta}^\sigma$, 曲率张量的协变、混合分支 $b_{\alpha\beta}$ 和 b_α^β 定义如下(显然它们依赖于变量 $\mathbf{y} \in \bar{\omega}$, 此处 $\mathbf{y} \in \bar{\omega}$ 被省掉)

$$a_{\alpha\beta} = \mathbf{e}_\alpha \cdot \mathbf{e}_\beta; a^{\alpha\beta} = \mathbf{e}^\alpha \cdot \mathbf{e}^\beta; a^{\alpha\beta} a_{\beta\lambda} = \delta_\lambda^\alpha$$

$$\Gamma_{\alpha\beta}^\sigma = \mathbf{e}^\sigma \cdot \partial_\beta \mathbf{e}_\alpha; b_{\alpha\beta} = \mathbf{n} \cdot \partial_\beta \mathbf{e}_\alpha; b_\alpha^\beta = a^{\beta\sigma} b_{\sigma\alpha}$$

度量张量的行列式为 $\mathbf{a} := \det(a_{\alpha\beta})$, 此外给出置换张量如下^[8]

$$\epsilon_{\alpha\beta} = \begin{cases} a^{\frac{1}{2}} \\ -a^{\frac{1}{2}} \\ 0 \end{cases}$$

$$\epsilon^{\alpha\beta} = \begin{cases} a^{-\frac{1}{2}} & (\alpha, \beta): (1, 2) \text{ 的偶置换} \\ -a^{-\frac{1}{2}} & (\alpha, \beta): (1, 2) \text{ 的奇置换} \\ 0 & \text{其他} \end{cases}$$

S 上的协变导数定义^[8]为 $\nabla_\alpha b_\tau^\sigma = \partial b_\tau^\sigma / \partial y^\alpha + \Gamma_{\alpha\tau}^\sigma b_\tau^\sigma - \Gamma_{\alpha\tau}^\sigma b_\tau^\sigma$.

2 主要结论

给出壳体中性面发生形变时度量张量改变量的

完整表达式.

定理 1 假定 $\boldsymbol{\eta} = \eta^i \mathbf{e}_i$ 是定义在 $S = \boldsymbol{\theta}(\bar{\omega})$ 上的向量场, $a_{\alpha\beta}$ 和 $a_{\alpha\beta}(\boldsymbol{\eta})$ 分别是定义在中性面 $S = \boldsymbol{\theta}(\bar{\omega})$ 和 $S(\boldsymbol{\eta}) = (\boldsymbol{\theta} + \boldsymbol{\eta})(\bar{\omega})$ 上的度量张量, 则有如下式子成立

$$a_{\alpha\beta}(\boldsymbol{\eta}) - a_{\alpha\beta} = 2\gamma_{\alpha\beta}(\boldsymbol{\eta}) + \varphi_{\alpha\beta}(\boldsymbol{\eta})$$

其中

$$\gamma_{\alpha\beta}(\boldsymbol{\eta}) := \frac{1}{2} (a_{\beta\sigma} \overset{\circ}{\nabla}_\alpha \eta^\sigma + a_{\alpha\lambda} \overset{\circ}{\nabla}_\beta \eta^\lambda)$$

$$\varphi_{\alpha\beta}(\boldsymbol{\eta}) := a_{ij} \overset{\circ}{\nabla}_\alpha \eta^i \overset{\circ}{\nabla}_\beta \eta^j$$

$$a_{ij} = \{a_{\alpha\beta}, i = \alpha, j = \beta, a_{3\alpha} = a_{\alpha 3} = 0, a_{33} = 0\}$$

$$\overset{\circ}{\nabla}_\alpha \eta^\sigma = \overset{*}{\nabla}_\alpha \eta^\sigma - b_\alpha^\sigma \eta^3; \overset{\circ}{\nabla}_\alpha \eta^3 = \overset{*}{\nabla}_\alpha \eta^3 + b_{\alpha\lambda} \eta^\lambda$$

如果 $\boldsymbol{\eta}$ 充分小, 则 $\varphi_{\alpha\beta}(\boldsymbol{\eta})$ 是高阶项.

证明 令 $\boldsymbol{\eta}$ 是 S 上 S -坐标系的基向量, 即 $\boldsymbol{\eta} = \eta^\lambda \mathbf{e}_\lambda + \eta^3 \mathbf{n}$, 则

$$\boldsymbol{\eta}_\alpha = \partial_\alpha \boldsymbol{\eta} = \partial_\alpha (\eta^\lambda \mathbf{e}_\lambda + \eta^3 \mathbf{n}) =$$

$$\partial_\alpha \eta^\lambda \mathbf{e}_\lambda + \eta^\lambda \partial_\alpha \mathbf{e}_\lambda + \partial_\alpha \eta^3 \mathbf{n} + \eta^3 \partial_\alpha \mathbf{n}$$

由 Gauss 和 Weingarten 公式, 有

$$\mathbf{e}_{\alpha\lambda} = \Gamma_{\alpha\lambda}^\sigma \mathbf{e}_\sigma + b_{\alpha\lambda} \mathbf{n}, \mathbf{n}_\alpha = -b_\alpha^\sigma \mathbf{e}_\sigma$$

则 $\boldsymbol{\eta}_\alpha = (\overset{*}{\nabla}_\alpha \eta^\sigma - b_\alpha^\sigma \eta^3) \mathbf{e}_\sigma + (\overset{*}{\nabla}_\alpha \eta^3 + b_{\alpha\lambda} \eta^\lambda) \mathbf{n}$. 令 $\overset{\circ}{\nabla}_\alpha \eta^\sigma = \overset{*}{\nabla}_\alpha \eta^\sigma - b_\alpha^\sigma \eta^3$, $\overset{\circ}{\nabla}_\alpha \eta^3 = \overset{*}{\nabla}_\alpha \eta^3 + b_{\alpha\lambda} \eta^\lambda$, 则 $\boldsymbol{\eta}_\alpha$ 变为

$$\boldsymbol{\eta}_\alpha = \overset{\circ}{\nabla}_\alpha \eta^\sigma \mathbf{e}_\sigma + \overset{\circ}{\nabla}_\alpha \eta^3 \mathbf{n} \quad (1)$$

因此, 变形中性面 $S(\boldsymbol{\eta})$ 上的基向量是

$$\mathbf{e}_\alpha(\boldsymbol{\eta}) = \partial_\alpha (\boldsymbol{\theta} + \boldsymbol{\eta}) = \mathbf{e}_\alpha + \overset{\circ}{\nabla}_\alpha \eta^\sigma \mathbf{e}_\sigma + \overset{\circ}{\nabla}_\alpha \eta^3 \mathbf{n} =$$

$$(\delta_\alpha^\sigma + \overset{\circ}{\nabla}_\alpha \eta^\sigma) \mathbf{e}_\sigma + \overset{\circ}{\nabla}_\alpha \eta^3 \mathbf{n} \quad (2)$$

则 $S(\boldsymbol{\eta})$ 上的度量张量为

$$a_{\alpha\beta}(\boldsymbol{\eta}) = a_{\alpha\beta} + a_{\alpha\lambda} \overset{\circ}{\nabla}_\beta \eta^\lambda + a_{\beta\sigma} \overset{\circ}{\nabla}_\alpha \eta^\sigma +$$

$$a_{\lambda\sigma} \overset{\circ}{\nabla}_\alpha \eta^\sigma \overset{\circ}{\nabla}_\beta \eta^\lambda + \overset{\circ}{\nabla}_\alpha \eta^3 \overset{\circ}{\nabla}_\beta \eta^3 \quad (3)$$

由 $\overset{\circ}{\nabla}_{\alpha\beta\gamma} = 0$, 有

$$\gamma_{\alpha\beta}(\boldsymbol{\eta}) := \frac{1}{2} (\overset{\circ}{\nabla}_\alpha \eta_\beta + \overset{\circ}{\nabla}_\beta \eta_\alpha) =$$

$$\frac{1}{2} (a_{\beta\sigma} \overset{\circ}{\nabla}_\alpha \eta^\sigma + a_{\alpha\lambda} \overset{\circ}{\nabla}_\beta \eta^\lambda)$$

令

$$\varphi_{\alpha\beta}(\boldsymbol{\eta}) := a_{\lambda\sigma} \overset{\circ}{\nabla}_\alpha \eta^\sigma \overset{\circ}{\nabla}_\beta \eta^\lambda + \overset{\circ}{\nabla}_\alpha \eta^3 \overset{\circ}{\nabla}_\beta \eta^3 = a_{ij} \eta^i \overset{\circ}{\nabla}_\alpha \eta^j$$

则式(3)改写为 $a_{\alpha\beta}(\boldsymbol{\eta}) - a_{\alpha\beta} = 2\gamma_{\alpha\beta}(\boldsymbol{\eta}) + \varphi_{\alpha\beta}(\boldsymbol{\eta})$. 证毕.

定理 1 说明度量张量的改变量由两部分组成, 一部分是 S 上的变形张量 $\gamma_{\alpha\beta}(\boldsymbol{\eta})$, 另一部分是关于 $\boldsymbol{\eta}$ 的二阶多项式 $\varphi_{\alpha\beta}(\boldsymbol{\eta}) = O(|\boldsymbol{\eta}|^2)$.

为了得到曲率张量的改变量, 先给出两个引理.

第 1 个引理给出壳体中性面发生形变时度量张量行列式的变化情况,第 2 个引理研究壳体中性面发生形变后的单位法向量.

引理 1 在定理 1 的假设下, a 和 $a(\eta)$ 分别是 $S=\theta(\bar{\omega})$ 和 $S(\eta)=(\theta+\eta)(\bar{\omega})$ 上度量张量的行列式. 令 $q^{-2}:=a(\eta)/a$, 则有 $q^{-2}:=1+2\gamma_0(\eta)+\pi(\eta)$ 成立, 其中 $\gamma_0(\eta)$ 和 $\pi(\eta)$ 定义如下

$$\left. \begin{aligned} \gamma_0(\eta) &= a^{\alpha\beta}\gamma_{\alpha\beta}(\eta); \varphi_0(\eta) = a^{\alpha\beta}\varphi_{\alpha\beta}(\eta) \\ \epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\gamma_{\alpha\beta}(\eta)\gamma_{\lambda\sigma}(\eta) &= \frac{1}{a}\det(\gamma_{\alpha\beta}(\eta)) \\ \epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\varphi_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta) &= \frac{1}{a}\det(\varphi_{\alpha\beta}(\eta)) \\ \pi(\eta) &= \varphi_0(\eta) + 2\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\gamma_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta) + \\ &\quad \frac{2}{a}\det(\gamma_{\alpha\beta}(\eta)) + \frac{1}{2a}\det(\varphi_{\alpha\beta}(\eta)) = o(|\eta|^2) \end{aligned} \right\} \quad (4)$$

证明 由定理 1, $S(\eta)=(\theta+\eta)(\bar{\omega})$ 上的度量张量的行列式为

$$\begin{aligned} a(\eta) &= a + a\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}(\eta)(a_{\alpha\beta}\gamma_{\lambda\sigma}(\eta) + a_{\lambda\sigma}\gamma_{\alpha\beta}(\eta)) + \\ &\quad \frac{1}{2}a\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}(a_{\alpha\beta}\varphi_{\lambda\sigma}(\eta) + a_{\lambda\sigma}\varphi_{\alpha\beta}(\eta)) + \\ &\quad a\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}(\gamma_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta) + \gamma_{\lambda\sigma}(\eta)\varphi_{\alpha\beta}(\eta)) + \\ &\quad 2a\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\gamma_{\alpha\beta}(\eta)\gamma_{\lambda\sigma}(\eta) + \frac{1}{2}a\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\varphi_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta) \end{aligned} \quad (5)$$

令 $\gamma_0(\eta):=a^{\alpha\beta}\gamma_{\alpha\beta}(\eta)$, $\varphi_0(\eta):=a^{\alpha\beta}\varphi_{\alpha\beta}(\eta)$. 由置换张量的反对称性 $\epsilon^{\alpha\beta}=-\epsilon^{\beta\alpha}$ 和 $\gamma_{\alpha\beta}$, $\varphi_{\alpha\beta}$ 的对称性 $\gamma_{\alpha\beta}=\gamma_{\beta\alpha}$, $\varphi_{\alpha\beta}=\varphi_{\beta\alpha}$, 则式(5)变为

$$\begin{aligned} a(\eta) &= a + \\ &\quad 2a\gamma_0(\eta) + a\varphi_0(\eta) + 2a\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\gamma_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta) + \\ &\quad a\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\left(2\gamma_{\alpha\beta}(\eta)\gamma_{\lambda\sigma}(\eta) + \frac{1}{2}\varphi_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta)\right) \end{aligned}$$

因此

$$q^{-2}:=\frac{a(\eta)}{a}=$$

$$1+2\gamma_0(\eta)+\varphi_0(\eta)+2\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\gamma_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta)+\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\left(2\gamma_{\alpha\beta}(\eta)\gamma_{\lambda\sigma}(\eta)+\frac{1}{2}\varphi_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta)\right)$$

由

$$\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\gamma_{\alpha\beta}(\eta)\gamma_{\lambda\sigma}(\eta)=\frac{1}{a}\det(\gamma_{\alpha\beta}(\eta))$$

$$\epsilon^{\alpha\lambda}\epsilon^{\beta\sigma}\varphi_{\alpha\beta}(\eta)\varphi_{\lambda\sigma}(\eta)=\frac{1}{a}\det(\varphi_{\alpha\beta}(\eta))$$

最终 $q^{-2}:=1+2\gamma_0(\eta)+\pi(\eta)$, 其中 $\gamma_0(\eta)$ 和 $\pi(\eta)$ 由式(4)给出. 证毕.

引理 2 在定理 1 的假设下, n 和 $n(\eta)$ 分别是 $S=$

$\theta(\bar{\omega})$ 和 $S(\eta)=(\theta+\eta)(\bar{\omega})$ 上的外法向, 则有如下公式成立

$$\begin{aligned} n(\eta) &= q[(1+\gamma_0(\eta)+\det(\overset{\circ}{\nabla}_a\eta^3))n + \\ &\quad (-\delta_\nu^\alpha + \epsilon^{\alpha\beta}\epsilon_{\sigma\nu}\overset{\circ}{\nabla}_a\eta^\sigma)\overset{\circ}{\nabla}_a\eta^3e^\nu] \end{aligned}$$

证明 由

$$n(\eta) = \frac{1}{2}\epsilon^{\alpha\beta}(\eta)e_\alpha(\eta) \wedge e_\beta(\eta) \quad (6)$$

将式(2)代入式(6), 应用 $\epsilon^{\alpha\beta}(\eta) = \left(\frac{a}{a(\eta)}\right)^{1/2}\epsilon^{\alpha\beta}$, 有

$$\begin{aligned} n(\eta) &= \frac{1}{2}\epsilon^{\alpha\beta}[(\delta_\alpha^\lambda + \overset{\circ}{\nabla}_a\eta^\lambda)(\delta_\beta^\sigma + \overset{\circ}{\nabla}_\beta\eta^\sigma)e_\lambda \wedge e_\sigma + \\ &\quad (\delta_\alpha^\lambda + \overset{\circ}{\nabla}_a\eta^\lambda)\overset{\circ}{\nabla}_\beta\eta^3e_\lambda \wedge n + \\ &\quad (\delta_\beta^\sigma + \overset{\circ}{\nabla}_\beta\eta^\sigma)\overset{\circ}{\nabla}_a\eta^3n \wedge e_\sigma] \end{aligned}$$

由 $e_\alpha \wedge e_\beta = \epsilon_{\alpha\beta}n$, $n \wedge e_\alpha = \epsilon_{\alpha\beta}e^\beta$, $\epsilon^{\alpha\beta}\epsilon_{\alpha\lambda} = \delta_\lambda^\beta$, 则

$$\begin{aligned} n(\eta) &= \frac{1}{2}q[2 + 2\overset{\circ}{\nabla}_\beta\eta^\beta + \epsilon^{\alpha\beta}\epsilon_{\lambda\sigma}\overset{\circ}{\nabla}_a\eta^\lambda\overset{\circ}{\nabla}_\beta\eta^\sigma]n + \\ &\quad [(-\delta_\nu^\alpha + \epsilon^{\alpha\beta}\epsilon_{\sigma\nu}\overset{\circ}{\nabla}_\beta\eta^\sigma)\overset{\circ}{\nabla}_a\eta^3 - \\ &\quad (\delta_\nu^\beta + \epsilon^{\alpha\beta}\epsilon_{\lambda\nu}\overset{\circ}{\nabla}_a\eta^\lambda)\overset{\circ}{\nabla}_\beta\eta^3]e^\nu] \end{aligned}$$

由

$$\begin{aligned} \epsilon^{\alpha\beta}\overset{\circ}{\nabla}_\beta\eta^\lambda\overset{\circ}{\nabla}_a\eta^3 &= -\epsilon^{\beta\alpha}\overset{\circ}{\nabla}_\beta\eta^\lambda\overset{\circ}{\nabla}_a\eta^3 = \\ &= -\epsilon^{\alpha\beta}\overset{\circ}{\nabla}_a\eta^\lambda\overset{\circ}{\nabla}_\beta\eta^3 \end{aligned} \quad (7)$$

则 $n(\eta)$ 变为

$$\begin{aligned} n(\eta) &= q\left[\left(1 + \overset{\circ}{\nabla}_\beta\eta^\beta + \frac{1}{2}\epsilon^{\alpha\beta}\epsilon_{\lambda\sigma}\overset{\circ}{\nabla}_a\eta^\lambda\overset{\circ}{\nabla}_\beta\eta^\sigma\right)n + \right. \\ &\quad \left. (-\overset{\circ}{\nabla}_\nu\eta^3 + \epsilon^{\alpha\beta}\epsilon_{\sigma\nu}\overset{\circ}{\nabla}_\beta\eta^\sigma\overset{\circ}{\nabla}_a\eta^3)e^\nu\right] \end{aligned}$$

注意 $\overset{\circ}{\nabla}_\beta\eta^\beta = \overset{*}{\nabla}_\beta\eta^\beta - 2H\eta^3 = \gamma_0(\eta)$ 和 $\epsilon^{\alpha\beta}\epsilon_{\lambda\sigma}\overset{\circ}{\nabla}_a\eta^\lambda\overset{\circ}{\nabla}_\beta\eta^\sigma = 2\det(\overset{\circ}{\nabla}_a\eta^3)$, 因此

$$\begin{aligned} n(\eta) &= q[(1+\gamma_0(\eta)+\det(\overset{\circ}{\nabla}_a\eta^3))n + \\ &\quad (-\delta_\nu^\alpha + \epsilon^{\alpha\beta}\epsilon_{\sigma\nu}\overset{\circ}{\nabla}_\beta\eta^\sigma)\overset{\circ}{\nabla}_a\eta^3e^\nu] \end{aligned} \quad (8)$$

定理 2 在定理 1 的假设下, 令 $b_{\alpha\beta}$ 和 $b_{\alpha\beta}(\eta)$ 分别是 $S=\theta(\bar{\omega})$ 和 $S(\eta)=(\theta+\eta)(\bar{\omega})$ 上的曲率张量, 则有 $b_{\alpha\beta}(\eta)-b_{\alpha\beta}=\rho_{\alpha\beta}(\eta)+\Psi_{\alpha\beta}(\eta)$, 其中 $\rho_{\alpha\beta}(\eta)$ 和 $\Psi_{\alpha\beta}(\eta)$ 定义如下

$$\begin{aligned} \rho_{\alpha\beta}(\eta) &:= \frac{1}{2}[\overset{*}{\nabla}_\beta\overset{\circ}{\nabla}_a\eta^3 + \overset{*}{\nabla}_a\overset{\circ}{\nabla}_\beta\eta^3 + \\ &\quad b_{\beta\lambda}\overset{\circ}{\nabla}_a\eta^\lambda + b_{\alpha\lambda}\overset{\circ}{\nabla}_\beta\eta^\lambda] \end{aligned}$$

$$\begin{aligned} \Psi_{\alpha\beta}(\eta) &:= (q-1)(b_{\alpha\beta} + \rho_{\alpha\beta}(\eta)) + \\ &\quad q[b_{\alpha\beta}\gamma_0(\eta) + N_{\alpha\beta}^2(\eta) + N_{\alpha\beta}^3(\eta)] \end{aligned}$$

$$\begin{aligned} N_{\alpha\beta}^2(\eta) &:= b_{\alpha\beta}\det(\overset{\circ}{\nabla}_a\eta^3) - \Phi_{\alpha\beta}^*(\eta)\overset{\circ}{\nabla}_\sigma\eta^3 + \\ &\quad \gamma_0(\eta)(\rho_{\alpha\beta}(\eta) + \Gamma_{\alpha\beta}^*\overset{\circ}{\nabla}_\sigma\eta^3) + \end{aligned}$$

$$\begin{aligned}
& (\varepsilon^{\nu\mu}\varepsilon_{\sigma\lambda} - \delta_{\sigma\lambda}^{\nu\mu}) \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\nu \eta^\sigma \overset{0}{\nabla}_\mu \eta^\sigma \\
N_{\alpha\beta}^3(\boldsymbol{\eta}) & := (\rho_{\alpha\beta}(\boldsymbol{\eta}) + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\lambda \eta^3) \det(\overset{0}{\nabla}_\alpha \eta^\beta) + \\
& (\Phi_{\alpha\beta}^s(\boldsymbol{\eta}) + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\lambda \eta^\sigma) \varepsilon^{\nu\mu} \varepsilon_{\sigma\tau} \overset{0}{\nabla}_\nu \eta^\tau \overset{0}{\nabla}_\mu \eta^3) \\
\Phi_{\alpha\beta}^s(\boldsymbol{\eta}) & := \\
\frac{1}{2} [& \overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^\sigma + \overset{*}{\nabla}_\alpha \overset{0}{\nabla}_\beta \eta^\sigma + b_{\beta\lambda}^s \overset{0}{\nabla}_\alpha \eta^\lambda + b_{\alpha\lambda}^s \overset{0}{\nabla}_\beta \eta^\lambda]
\end{aligned}$$

备注:如果 $\boldsymbol{\eta}$ 充分小,则 $\varphi_{\alpha\beta}(\boldsymbol{\eta})$ 是高阶项.

证明 令 $e_{\alpha\beta} = \partial_\alpha \mathbf{e}_\beta$, 由 Gauss 和 Weingarten 公式, 有 $e_{\alpha\beta} = \Gamma_{\alpha\beta}^* \mathbf{e}_\lambda + b_{\alpha\beta} \mathbf{n}$. 中性面变形后, $e_{\alpha\beta}$ 变为

$$\begin{aligned}
e_{\alpha\beta}(\boldsymbol{\eta}) & = \alpha_\beta(\mathbf{e}_\alpha + \boldsymbol{\eta}_\alpha) = \\
e_{\alpha\beta} + \partial_\beta \eta_\alpha & = \Gamma_{\alpha\beta}^* \mathbf{e}_\lambda + b_{\alpha\beta} \mathbf{n} + \partial_\beta \eta_\alpha \quad (9)
\end{aligned}$$

由式(1),有

$$\begin{aligned}
\partial_\beta \eta_\alpha & = [\overset{0}{\nabla}_\alpha \eta^\sigma \Gamma_{\sigma\beta}^* + \partial_\beta \overset{0}{\nabla}_\alpha \eta^\lambda - \overset{0}{\nabla}_\alpha \eta^3 b_{\beta\lambda}^s] \mathbf{e}_\lambda + \\
& [\overset{0}{\nabla}_\alpha \eta^\sigma b_{\sigma\beta} + \partial_\beta \overset{0}{\nabla}_\alpha \eta^3] \mathbf{n}
\end{aligned}$$

由

$$\partial_\beta \overset{0}{\nabla}_\alpha \eta^\lambda = \overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^\lambda - \Gamma_{\sigma\beta}^* \overset{0}{\nabla}_\alpha \eta^\sigma + \Gamma_{\sigma\beta}^* \overset{0}{\nabla}_\sigma \eta^\lambda$$

且 $\partial_\beta \overset{0}{\nabla}_\alpha \eta^3 = \overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^3 + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\lambda \eta^3$, 则有

$$\begin{aligned}
\partial_\beta \eta_\alpha & = (\overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^\lambda + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\sigma \eta^\sigma - \overset{0}{\nabla}_\alpha \eta^3 b_{\beta\lambda}^s) \mathbf{e}_\lambda + \\
& (\overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^3 + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\lambda \eta^3 + \overset{0}{\nabla}_\alpha \eta^\sigma b_{\sigma\beta}) \mathbf{n} \quad (10)
\end{aligned}$$

将式(10)带入式(9),则有

$$\begin{aligned}
e_{\alpha\beta}(\boldsymbol{\eta}) & = (\overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^\lambda + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\sigma \eta^\sigma + \Gamma_{\alpha\beta}^* - \overset{0}{\nabla}_\alpha \eta^3 b_{\beta\lambda}^s) \mathbf{e}_\lambda + \\
& (\overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^3 + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\lambda \eta^3 + \overset{0}{\nabla}_\alpha \eta^\sigma b_{\sigma\beta} + b_{\alpha\beta}) \mathbf{n}
\end{aligned}$$

类似地可以得到 $e_{\beta\alpha}(\boldsymbol{\eta})$, 因此

$$e_{\alpha\beta}(\boldsymbol{\eta}) = \frac{1}{2} (e_{\alpha\beta}(\boldsymbol{\eta}) + e_{\beta\alpha}(\boldsymbol{\eta}))$$

令

$$\begin{aligned}
\rho_{\alpha\beta}(\boldsymbol{\eta}) & := \\
\frac{1}{2} [& (\overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^3 + \overset{*}{\nabla}_\alpha \overset{0}{\nabla}_\beta \eta^3 + b_{\beta\lambda}^s \overset{0}{\nabla}_\alpha \eta^\lambda + b_{\alpha\lambda}^s \overset{0}{\nabla}_\beta \eta^\lambda) \\
\Phi_{\alpha\beta}^s(\boldsymbol{\eta}) & := \\
\frac{1}{2} [& (\overset{*}{\nabla}_\beta \overset{0}{\nabla}_\alpha \eta^\sigma + \overset{*}{\nabla}_\alpha \overset{0}{\nabla}_\beta \eta^\sigma + b_{\beta\lambda}^s \overset{0}{\nabla}_\alpha \eta^\lambda + b_{\alpha\lambda}^s \overset{0}{\nabla}_\beta \eta^\lambda)
\end{aligned}$$

则

$$\begin{aligned}
e_{\alpha\beta}(\boldsymbol{\eta}) & = (\Gamma_{\alpha\beta}^* (\delta_{\alpha\lambda}^{\beta\lambda} + \overset{0}{\nabla}_\lambda \eta^\sigma) + \Phi_{\alpha\beta}^s(\boldsymbol{\eta})) \mathbf{e}_\sigma + \\
& (b_{\alpha\beta} + \rho_{\alpha\beta}(\boldsymbol{\eta}) + \Gamma_{\alpha\beta}^* \overset{0}{\nabla}_\lambda \eta^3) \mathbf{n} \quad (11)
\end{aligned}$$

由于 $b_{\alpha\beta}(\boldsymbol{\eta}) = e_{\alpha\beta}(\boldsymbol{\eta}) \cdot \mathbf{n}(\boldsymbol{\eta})$, 由式(7)和式(11) 有 $b_{\alpha\beta}(\boldsymbol{\eta}) = b_{\alpha\beta} + \rho_{\alpha\beta}(\boldsymbol{\eta}) + \Psi_{\alpha\beta}(\boldsymbol{\eta})$, 其中 $\rho_{\alpha\beta}(\boldsymbol{\eta})$ 和

$\Psi_{\alpha\beta}(\boldsymbol{\eta})$ 由式(8)定义. 证毕.

定理 2 表明, 曲率张量的改变量由两部分组成, 一部分是线性化部分 $\rho_{\alpha\beta}(\boldsymbol{\eta})$, 另一部分是关于 $\boldsymbol{\eta}$ 的三阶多项式 $\Psi_{\alpha\beta}(\boldsymbol{\eta}) = O(|\boldsymbol{\eta}|^3)$.

3 结 论

由 $a_{\alpha\beta}$ 的定义, 首先给出了壳体中性面发生形变时的度量张量改变量的完整形式. 这个结果与 Ciarlet 的表达式一致. 接着, 为了给出曲率张量改变量的完整形式, 证明了两个引理. 最后, 由两个引理和 $b_{\alpha\beta}$ 的定义, 给出了曲率张量改变量的完整形式, 这比 Ciarlet 的表达式更精确、更完整. 因为 Ciarlet 是用 $R_{\alpha\beta}^\#$ 代替 $R_{\alpha\beta}$, 给出的是曲率张量改变量的逼近形式.

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(编辑 杜秀杰)